

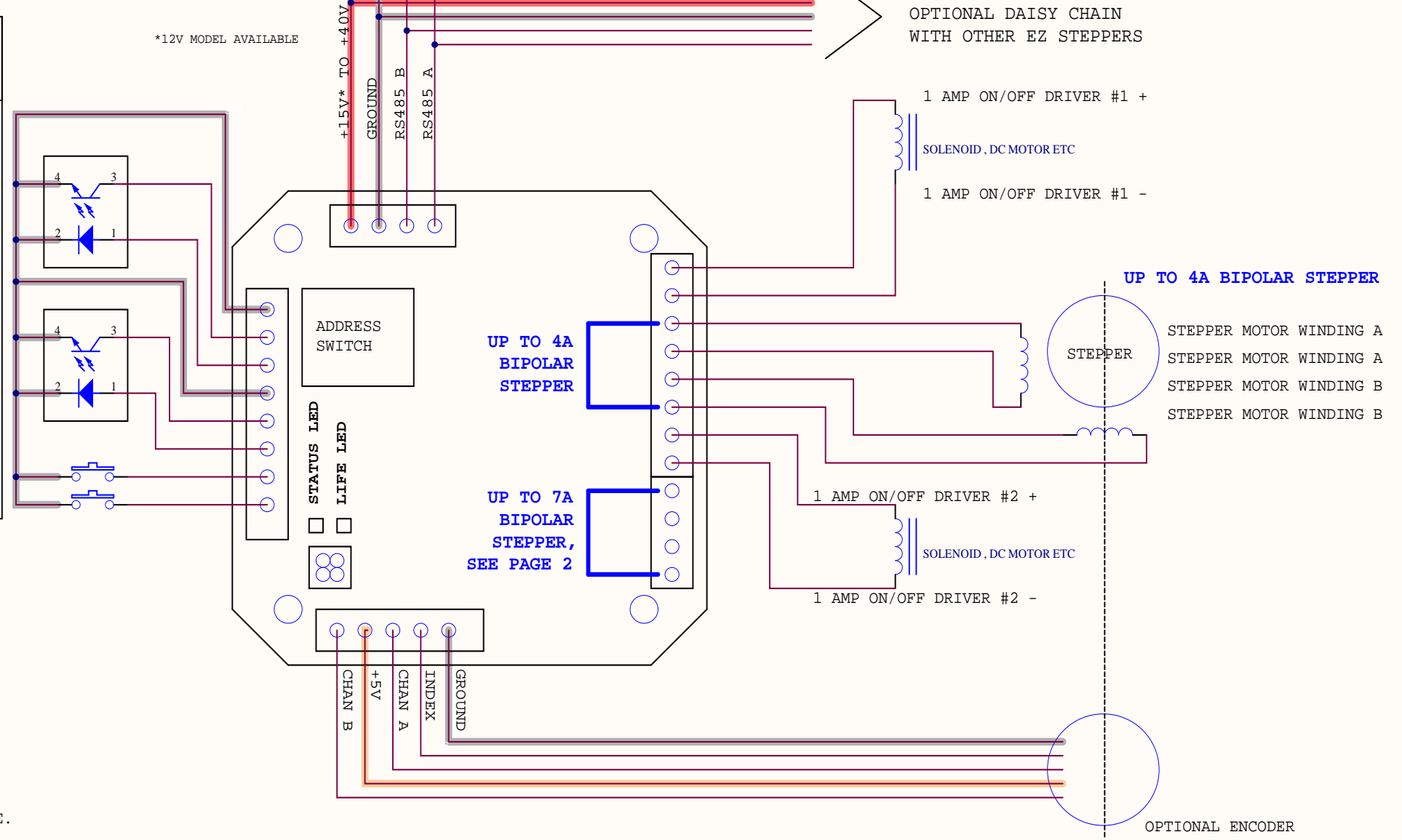
15V TO 40V SUPPLY

GROUND
+15V TO +40V
RS485 CONVERTER
DB9 TO COM PORT ON PC

TO PC COM PORT
USE 9600 BAUD
8BIT, NO PARITY,
1 STOP, NO FLOW CTRL.

MODE 2 STEP AND DIR IN	MODE 1 DUAL ENCODERS	JOG LIMIT MODE	MODE 0
		LOWER LIMIT	OPTO SENSOR #1 GROUND OPTO SENSOR #1 INPUT OPTO SENSOR #1 LED POWER OPTO SENSOR #2 GROUND
	INDEX 2	UPPER LIMIT	OPTO SENSOR #2 INPUT OPTO SENSOR #2 LED POWER
STEP IN DIR IN	CHAN A2 CHAN B2	JOG UP JOG DN	SWITCH #1 INPUT SWITCH #2 INPUT

*12V MODEL AVAILABLE



NOTES:

"H" OR HALT COMMAND WAITS FOR SWITCH #2 TO CHANGE STATE

"Z" OR HOME COMMAND RUNS MOTOR UNTIL OPTO #1 IS ON FLAG EDGE.

A SWITCH CAN REPLACE THE OPTO FOR HOMING, CONNECT SWITCH FROM PHOTO TRANSISTOR INPUT TO GROUND.

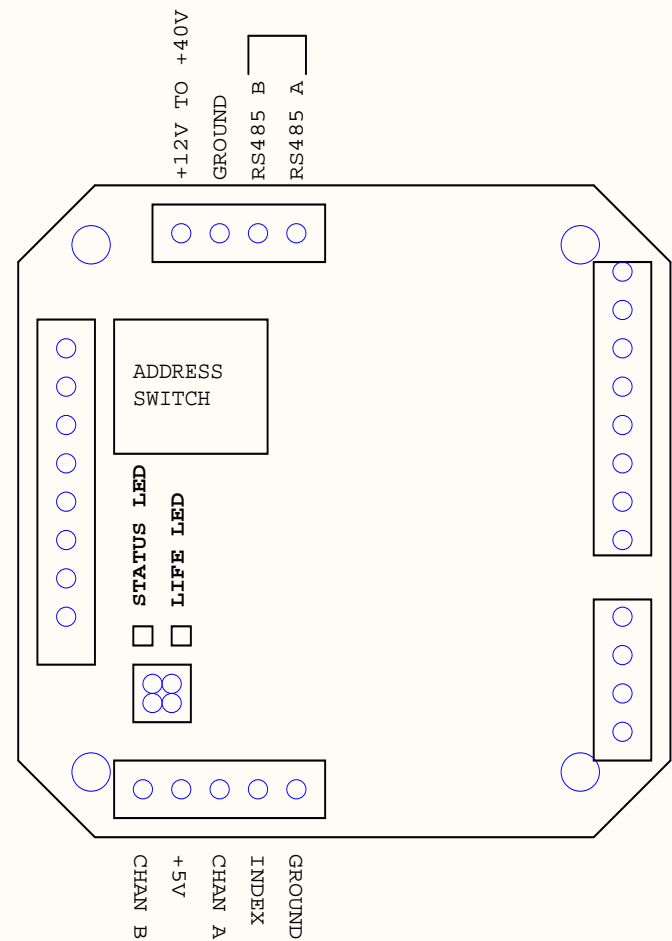
TOTAL CURRENT DRAW FROM ENCODERS + LEDS MUST BE < 200mA

DO NOT UNPLUG LOADS WHILE POWER IS ON

MODE 2 STEP AND DIR IN	MODE 1 DUAL ENCODERS	JOG LIMIT MODE	MODE 0
		LOWER LIMIT	DIGITAL I/O CONNECTOR OPTO SENSOR #1 GROUND OPTO SENSOR #1 INPUT OPTO SENSOR #1 LED POWER OPTO SENSOR #2 GROUND OPTO SENSOR #2 INPUT OPTO SENSOR #2 LED POWER <input type="checkbox"/> SWITCH #1 INPUT <input type="checkbox"/> SWITCH #2 INPUT
	INDEX 2	UPPER LIMIT	
STEP IN	CHAN A2	JOG UP	
DIR IN	CHAN B2	JOG DN	

4 SWITCH CLOSURE INPUTS
OR
2 OPTO INPUTS AND 2 SWITCH CLOSURE INPUTS

**EZBUS:
POWER INPUT AND
COMMUNICATION**



POWER OUTPUT DRIVERS

- 1 AMP ON/OFF DRIVER #1 +
- 1 AMP ON/OFF DRIVER #1 -
- STEPPER MOTOR WINDING A
- STEPPER MOTOR WINDING A
- STEPPER MOTOR WINDING B
- STEPPER MOTOR WINDING B
- 1 AMP ON/OFF DRIVER #2 +
- 1 AMP ON/OFF DRIVER #2 -

2 AMP; 1A CONTINUOUS

UP TO 4A BIPOLAR STEPPER

2 AMP; 1A CONTINUOUS

- HIGH CURRENT SCREW TERMINAL FOR STEPPER WINDING A
- HIGH CURRENT SCREW TERMINAL FOR STEPPER WINDING A
- HIGH CURRENT SCREW TERMINAL FOR STEPPER WINDING B
- HIGH CURRENT SCREW TERMINAL FOR STEPPER WINDING B

UP TO 7A BIPOLAR STEPPER

USE HIGH CURRENT SCREW TERMINAL FOR CURRENTS ABOVE 4A

MATING CONNECTORS:

- AMP MTA 100 SERIES
- 4PIN 22 GA DIGIKEY P/N A31122-ND (EZBUS CONNECTOR)
- 8PIN 22 GA DIGIKEY P/N A31111-ND (NEMA23 MOTOR)
- 8PIN 24 GA DIGIKEY P/N A31023-ND (NEMA17 MOTOR)
- 8PIN 26 GA DIGIKEY P/N A31030-ND (OPTO SWITCH CONNECTOR)
- T HANDLE CRIMP TOOL DIGIKEY P/N A9982-ND
- PISTOL GRIP TOOL DIGIKEY P/N A2031-ND WITH A1998-ND

MOTORS:

- 1) THE EZ STEPPER WILL DRIVE MOST STEPPER MOTORS
- 2) FOR BEST PERFORMANCE SELECT A MOTOR RATED AT ABOUT 1/4 OF THE SUPPLY VOLTAGE. Eg USE A 6V MOTOR WITH A 24V SUPPLY).
- 3) FOR (UNIPOLAR) STEPPER MOTORS WITH CENTER TAPPED WINDINGS , TYPICALLY LEAVE THE CENTER TAP UNCONNECTED, OR WIRE PER MANUFACTURERS RECOMMENDATIONS.

SUITABLE POWER SUPPLIES:

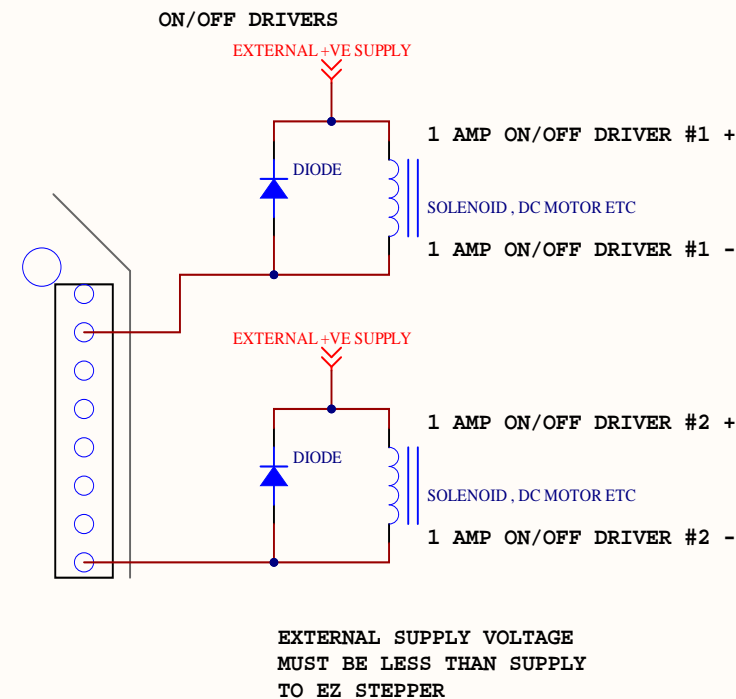
- 1) FOR FIRST TIME USERS, TO GUARD AGAINST A POSSIBLE MISWIRE, A CURRENT LIMITED LAB SUPPLY SET TO 12V AND 0.5A IS RECOMMENDED.
- 2) A SUPPLY OF 24V AND 2A CAPABILITY IS GOOD FOR MOST PURPOSES. POSSIBLE CHOICES ARE:
 - DIGIKEY P/N 271-1112-ND
 - DIGIKEY P/N Z1158-ND (ENCLOSED)
- 3) INPUT CURRENT IS MUCH LESS THAN MOTOR CURRENT DUE TO THE SWITCHING (PWM). IT CAN BE CALCULATED BY CONSIDERING CONSERVATION OF POWER. HOWEVER IT IS IMPORTANT TO MAKE SURE THAT THE SUPPLY WILL NOT FOLD BACK AS IT IS COMING UP SINCE THE EZ STEPPER WILL DRAW MORE CURRENT AT LOWER VOLTAGES.

OPTO HOME SWITCH:

- 1) "Z" OR HOME COMMAND RUNS MOTOR UNTIL OPTO #1 IS ON FLAG EDGE.
- 2) AN OPTO SWITCH PROVIDED WITH EACH STARTER KIT
- 3) USE TRANSISTOR OPTO THAT HAS $I_c > 1\text{mA}$ @ $I_F = 20\text{mA}$.
- 4) EXAMPLES OF ACCEPTABLE OPTOS ARE:
 - DIGIKEY P/N QVA11134-ND
 - DIGIKEY P/N H21A1-ND
 - HONEYWELL HOA1887-012 (IS PREWIRED)
 - HONEYWELL HOA1870-033 (IS PREWIRED)
 - OPTEK OPB830W11 (IS PREWIRED)
- 5) THE OPTO COUPLER LED PIN HAS $200\ \Omega$ TO 5V IN SERIES ON THE BOARD. THE $200\ \Omega$ CAN BE REMOVED IF DESIRED FOR RUNNING SENSORS THAT REQUIRE DIRECT ACCESS TO 5V. ON ON/OFF DRIVERS, THE COLLECTORS OF THE DRIVER TRANSISTORS HAVE $10\ \text{k}\Omega$ PULL-UPS TO 5V.
- 6) ALL INPUTS WORK ON TTL LEVEL SIGNALS

ON/OFF DRIVERS ALTERNATE WIRING DIAGRAM:

- 1) EACH ON/OFF DRIVER IS RATED AT 2 AMPS PEAK, 1 AMP CONTINUOUS
- 2) THE NEGATIVE PIN OF THESE DRIVERS IS ACTUALLY AN OPEN COLLECTOR TYPE OUTPUT THAT PULLS DOWN TO GROUND. IT IS POSSIBLE TO DRIVE LOADS THAT ARE OF A DIFFERENT VOLTAGE THAN THE SUPPLY VOLTAGE, BY CONNECTING THE POSITIVE SIDE OF THE LOAD TO AN EXTERNAL SUPPLY, AND THE NEGATIVE SIDE TO THE -VE OUTPUT PIN. HOWEVER, IN CASE THIS IS DONE IT IS NECESSARY TO PLACE AN EXTERNAL "FREE WHEELING" DIODE ACROSS ANY INDUCTIVE LOADS. EXTERNAL SUPPLY VOLTAGE MUST BE LESS THAN SUPPLY VOLTAGE BOARD
- 3) EXTERNAL DIODE IS NOT NECESSARY IF BOTH SIDES OF LOAD ARE WIRED BACK TO THE EZ STEPPER.

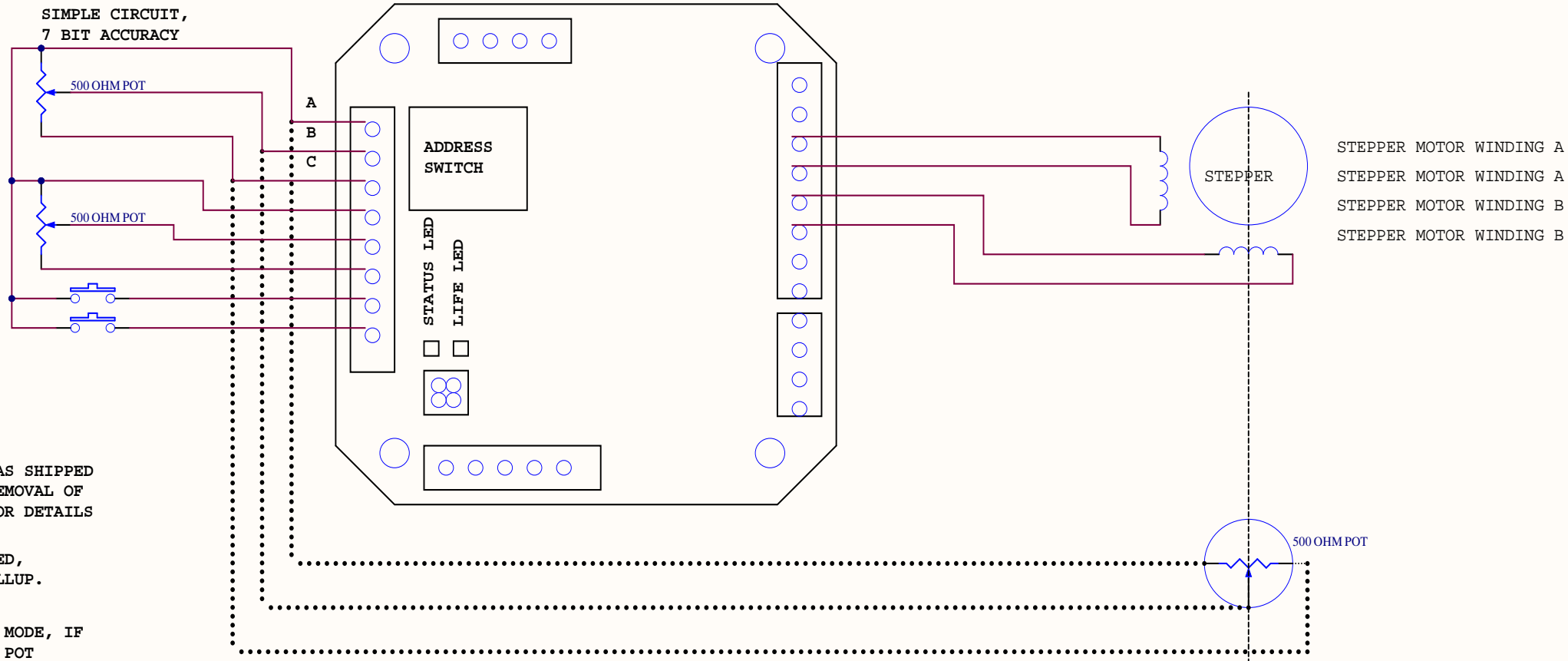


ACCESSORIES AND OTHER ELECTRICAL NOTES		
EZHR23ENHC	A04	
Wiring Diagram		
Print Date: 8/28/2023 1:43:25 PM	Sheet 3 of 5	6

FEEDBACK POT1 GROUND
 FEEDBACK POT1 WIPER
 FEEDBACK POT1 POWER

 POSITION COMMAND POT2 GROUND
 POSITION COMMAND POT2 WIPER
 POSITION COMMAND POT2 POWER

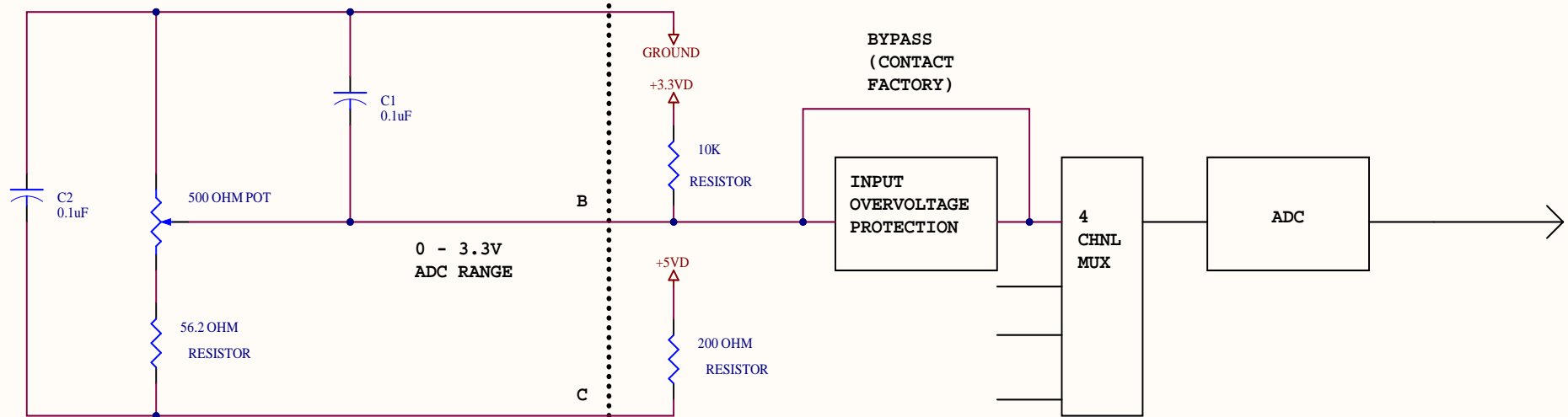
 SWITCH #1 CLOSURE TO GROUND INPUT
 SWITCH #2 CLOSURE TO GROUND INPUT



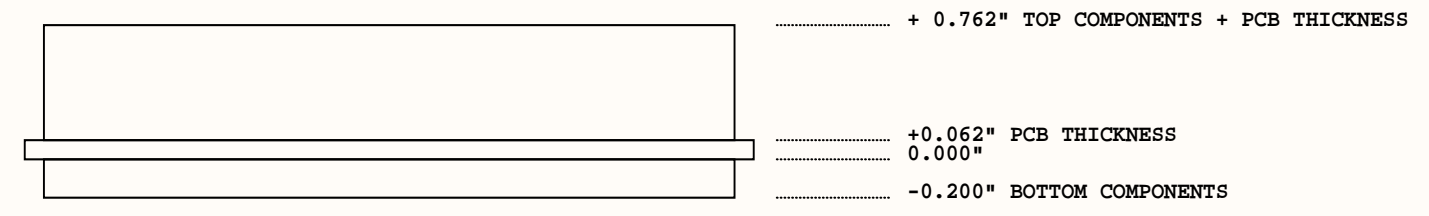
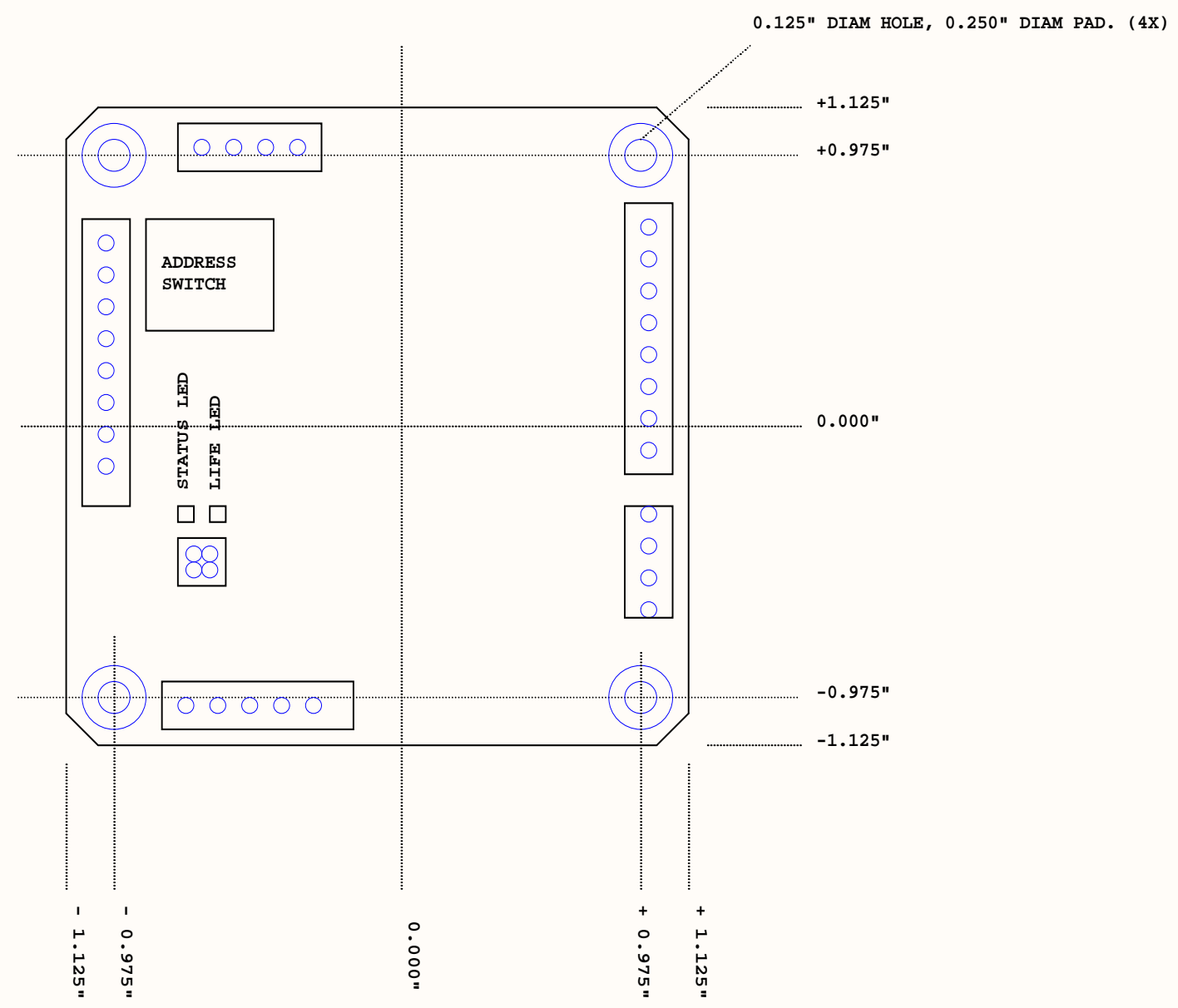
NOTES:

- 1) ALL 4 INPUTS ARE ANALOG INPUTS
- 2) ADC's VALUES RANGE FROM 0-16368. THE ACCURACY AS SHIPPED IS 7 BIT BUT CAN BE IMPROVED TO >10BIT WITH THE REMOVAL OF THE INPUT PROTECTION CIRCUITRY, CONTACT FACTORY FOR DETAILS
- 3) POTS IN THE RANGE OF 500 OHM - 10K ARE SUGGESTED, LOWER VALUES ARE LESS AFFECTED BY INTERNAL 10K PULLUP. 500 OHM RECOMMENDED.
- 4) IF USING POT FOR POSITION FEED BACK WITH /1N3R MODE, IF MOTOR EXHIBITS POSITIVE FEEDBACK, SWITCH ENDS OF POT
- 5) 10K INTERNAL PULLUP WILL INTERFERE WITH LINEARITY OF POT VOLTAGE, AND MAY NEED TO BE REMOVED - CONTACT FACTORY.
- 6) INPUT OVERVOLTAGE PROTECTION CIRCUITRY MAY NEED TO BE REMOVED FOR >7BIT ACCURACY - CONTACT FACTORY.

CIRCUITS INTERNAL TO DRIVE



ENHANCED EXTERNAL CIRCUIT FOR > 10BIT ACCURACY



<i>DIMENSIONS</i>		A04	
EZHR23ENHC			
Wiring Diagram			
Print Date: 8/28/2023 1:43:25 PM	Sheet 5 of 5		